## Geometric Deep Learning: From Pure Math to Applications

Jan E. Gerken



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Deep learning is lacking a strong theoretical foundation:

- Neural networks are complicated functions
- The training process is stochastic



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## Geometry of the training data



- Manifold Hypothesis: Data lies on low-dim. submanifold of high-dim. input space
- ▶ E.g. MNIST pictures lie on ~ 30-dim. submanifold of 28 × 28 = 784 dim. input space



## Learned diffeomorphisms

- How to characterize the data manifold?
- Can learn a diffeomorphism between a simple distribution and data distribution



- Diffeomorphism is given by another neural network, a normalizing flow
- Get access to the data manifold in a functional form
- Connections to shape matching
- Connections to optimal transport

[Jansson, Modin, 2022]

[Chen, Karlsson, Ringh, 2021] [Bauer, Joshi, Modin, 2017] [Onken, Fung, Li, Ruthotto 2020]

## Explainable AI (XAI)



- Neural network classifiers lack inherent interpretability
- > This is in contrast to more traditional methods like linear- or physical models
- ► For safety-critical applications this poses a serious challenge in practice
- Research progress can also be impeded
- Need explanations which provide insight into the neural network decisions

## Counterfactual explanations

- Counterfactual of a sample: Data point close to original but with different classification
- Difference between original and counterfactual reveals features which led to classification
- Example from CelebA dataset, classified as not-blonde:



original x



counterfactual x'



|x - x'|

## Adversarial Examples

Small perturbations can lead to misclassifications

$$p_{\text{blonde}}\left(\begin{array}{c} \hline \\ \hline \\ \end{array}\right) = 0.01 \quad \text{but} \quad p_{\text{blonde}}\left(\begin{array}{c} \hline \\ \\ \end{array}\right) = 0.99$$

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Reason: Classifier only trained on the data manifold



#### Counterfactuals

#### ► Can use normalizing flows to optimize along the data manifold ⇒ *counterfactuals*





original not blond

counterfactual<br/>blond ( $p \approx 0.99$ )adversarial example<br/>blond ( $p \approx 0.99$ )



 $x^{(i+1)} = x^{(i)} + \lambda \, \boldsymbol{\gamma^{-1}} \frac{\partial f_t}{\partial x}(x^{(i)}) + \mathcal{O}(\lambda^2)$ 

#### Data coordinates



Assume that data lies in a region S = supp(p) around data manifold D, in data coordinates x<sup>α</sup>

$$S_{x} = \left\{ x_{D} + x_{\delta} \mid x_{D} \in D_{x}, \ x_{\delta}^{\alpha} \in \left( -\frac{\delta}{2}, \frac{\delta}{2} \right) \right\}$$

with  $\delta \ll 1$ .

• Define normal coordinates  $y^{\mu}$  in a neighborhood of D

#### Gradient ascent in y-coordinates

• By choosing  $\{n_i\}$  orthogonal wrt  $\gamma$ , the inverse induced metric takes the form

$$\gamma^{\mu\nu}(y) = \begin{pmatrix} \gamma_D^{-1}(y) & & & \\ & \gamma_{\perp_1}^{-1} & & \\ & & \ddots & \\ & & & & \gamma_{\perp_{N_X-N_D}}^{-1} \end{pmatrix}^{\mu}$$

• The gradient ascent update  $g^{\alpha}(z^{(i+1)}) = g^{\alpha}(z^{(i)}) + \lambda \gamma^{\alpha\beta} \frac{\partial f_t}{\partial x^{\beta}} + O(\lambda^2)$  becomes

$$\gamma^{\alpha\beta}\frac{\partial f_t}{\partial x^\beta} = \frac{\partial x^\alpha}{\partial y^\mu_{\parallel}}\gamma^{\mu\nu}_D\frac{\partial f_t}{\partial y^\nu_{\parallel}} + \frac{\partial x^\alpha}{\partial y^i_{\perp}}\gamma^{-1}_{\perp i}\frac{\partial f_t}{\partial y^i_{\perp}}$$

• For  $\gamma_{\perp_i}^{-1} \to 0$  and  $\frac{\partial x}{\partial y_{\perp}}$  bounded we have

$$\gamma^{\alpha\beta}\frac{\partial f_t}{\partial x^\beta} \to \frac{\partial x^\alpha}{\partial y^\mu_{\parallel}}\gamma^{\mu\nu}_D\frac{\partial f_t}{\partial y^\nu_{\parallel}}$$

and hence the update step points along the data manifold.

 $\Rightarrow$  In this case, obtain counterfactuals, not adversarial examples!

#### Theorem (Diffeomorphic Counterfactuals)

For  $\epsilon \in (0, 1)$  and *g* a normalizing flow with Kullback–Leibler divergence KL(*p*, *q*) <  $\epsilon$ ,

$$\gamma_{\perp_i}^{-1} \to 0 \quad \text{as} \quad \delta \to 0$$

for all  $i \in \{1, ..., N_X - N_D\}$ .

# $\Rightarrow$ For well-trained generative models, the gradient ascent update in Z stays on the data manifold

## Toy example



## Diffeomorphic Counterfactuals with CelebA

- Classifier: Binary CNN trained on *blondelnot blonde* attribute (test accuracy: 94%)
- ► Flow: Glow

[Kingma et al., NeurIPS 2018]

• Task: Change classification from *not blonde* to *blonde* 



- Top row: Counterfactual computed in base space
- Bottom row: Adersarial example computed in data space

## Diffeomorphic Counterfactuals for regression

- Consider crowd-counting dataset of mall images
- Count number of people in the image
- ► Flow: Glow

Z

X

Optimize for low number of people

Optimize for high number of people



[Ribera et al., CVPR 2019]

[Kingma et al., NeurIPS 2018]

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- Geometry can help in several key parts of the learning process, bringing abstract mathematics to practical applications
  - Counterfactuals explain black-box classifiers by providing a realistic sample close to the original but with a different classification
  - Naive gradient ascent leads off the data manifold, yielding adversarial examples
  - Gradient ascent in the base space of a normalizing flow leads to optimization on the data manifold
  - Concept be used for a wide range of different problems

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  - Concept be used for a wide range of different problems
- New areas of mathematics enter the study of neural networks

#### Collaborators



Daniel Persson



Klaus-Robert Müller



Christoffer Petersson



Fredrik Ohlsson



Pan Kessel



Hampus Linander



Ann-Kathrin Dombrowsik



Oscar Carlsson



Jimmy Aronsson

